

Game Analysis & Strategic Design

Team 1732

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Agenda

- Step Zero
 - Team Goals
 - Team Capabilities
- Strategic Design
 - Game Analysis
 - Design Selection
- Example Season

Step Zero: Team Goals

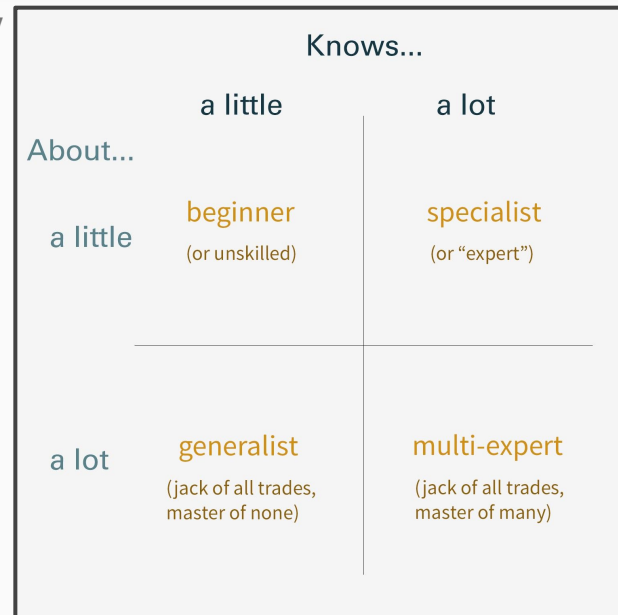
What do you want to achieve?

- Make SMART goals
- Examples:
 - Have a working robot in every match
 - Score a number of points per match
 - Play in eliminations (Be picked)
 - Be an alliance captain
 - Win a competition
- These goals will frame discussion about your robot design



Step Zero: Team Capabilities

- Assess your team capabilities and constraints honestly and realistically
 - Experience, machining access, budget, time
 - Even if you can build it, can you control it? Can you drive it?
- Jack of all trades, master of none
 - It's usually better to be great at one thing than average at everything
 - Consistency is key
- Account for scope and complexity
 - Several simple tasks will take the same or less time than a complex task

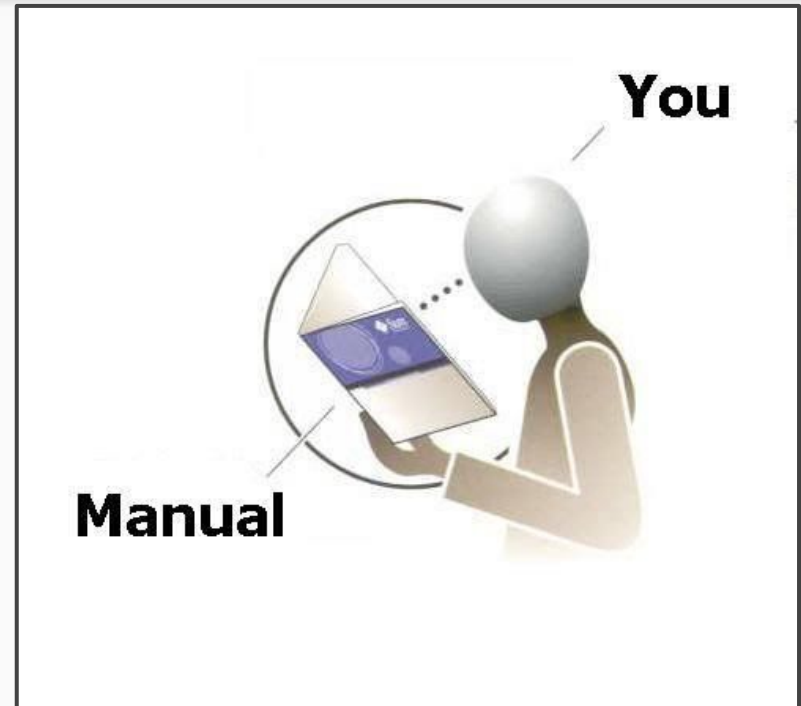


Step Zero: “Robot Points” Concept

- Let's say each team has a number of “Robot Points” to spend
 - Higher resource teams will have more Robot Points:
 - Low resource – <20 Points
 - Moderate Resource – 21-50 Points
 - High resource – 50+ Points
- Spend points to maximize resources
 - If you have 30 Robot Points, it's better to have 3 functions at 10/10 instead of 5 at 6/10
- Examples
 - Drivetrain
 - KoP Drive – 2
 - 6 Wheel West Coast – 6
 - Swerve – 12
 - Intake
 - Human Loaded – 2
 - Ground Pickup – 6
 - End game
 - Park - 0
 - Climb - 6
- Note:
 - These point values are made up, but you get the idea

Game Analysis: The Rules

- Read the manual
 - This will show the limits of what can be done in the game
- Read the manual
 - This should eliminate illegal game strategy ideas
- Read the manual
 - You may find loopholes or chokehold strategies
- Read the manual
 - The manual will be updated – some ideas may become illegal



Game Analysis: Scoring Breakdown

- Read the game summary and scoring details from the Game Manual
 - (The game video can be helpful, but is occasionally misleading)
- List every way to score points
 - High goal, low goal, drive to a zone, etc.
- What's the high score?
- How does the ranking system work?
 - FRC loves "Ranking Points" (RPs)

Example: 2020 game - Infinite Recharge

| Award | Awarded for... | AUTO | TELEOP | Qual. |
|-------------------------------------|---|------|--------|-----------------|
| INITIATION LINE | exit the infinite vertical volume created by the corresponding ALLIANCE'S INITIATION LINE any time before the end of AUTO (per ROBOT) | 5 | - | - |
| POWER CELLS | scored in BOTTOM PORT | 2 | 1 | - |
| | scored in OUTER PORT | 4 | 2 | - |
| | scored in INNER PORT | 6 | 3 | - |
| CONTROL PANEL | ROTATION CONTROL | - | 10 | - |
| | POSITION CONTROL | - | 20 | - |
| ENDGAME Points | HANG (per ROBOT) | - | 25 | - |
| | PARK (per ROBOT) | - | 5 | - |
| | LEVEL with 1-3 ROBOTS HANGING (per ALLIANCE) | - | 15 | - |
| SHIELD GENERATOR OPERATIONAL | earning at least sixty-five (65) ENDGAME points | - | - | 1 Ranking Point |
| SHIELD GENERATOR ENERGIZED | Stage 3 ACTIVATED | - | - | 1 Ranking Point |
| Tie | Completing a MATCH with the same number of points as your opponent | - | - | 1 Ranking Point |
| Win | Completing a MATCH with more points than your opponent | - | - | 2 Ranking Point |

| | Auto | | | | Tele-op | | | | Endgame | | | | Totals | |
|---------|--------------------|-----------|----------|----------|-----------|----------|----------|-------------------|-------------------|-------------|------------|--------------|--------|----------------|
| | Line Crossed (y/n) | Bottom PC | Outer PC | Inner PC | Bottom PC | Outer PC | Inner PC | CP Rotation (y/n) | CP Position (y/n) | Climb (y/n) | Park (y/n) | Level? (y/n) | Points | Alliance Total |
| Robot 1 | y | 3 | 0 | 0 | 3 | 6 | 0 | y | n | n | y | | 56 | 182 |
| Robot 2 | y | 3 | 0 | 0 | 5 | 5 | 1 | | | y | n | y | 54 | |
| Robot 3 | y | 0 | 3 | 0 | 0 | 15 | 0 | | | y | n | | 72 | |
| Robot 4 | y | 0 | 3 | 0 | 0 | 15 | 1 | y | y | y | n | | 120 | 274 |
| Robot 5 | y | 0 | 3 | 0 | 0 | 20 | 0 | | | y | n | y | 82 | |
| Robot 6 | y | 0 | 3 | 0 | 0 | 15 | 0 | | | y | n | | 72 | |

Game Analysis: Robot Tasks and Skills

- List all of the skills that a robot needs to complete game tasks
- Lump these skills together as they relate to different game tasks
- This list will help to create robot concepts

| Robot Skills |
|--|
| 1 Drive |
| 2 Drive over Small Bump |
| 3 Drive on ramp |
| 4 Drive (Most Terrain) |
| 5 Herd Boulder |
| 6 Hold Boulder |
| 7 Receive Boulder from Lower Wall Hole |
| 8 Receive Boulder from Upper Wall Hole |
| 9 Pick Up Boulder |
| 10 Shoot Boulder |
| 11 Release Boulder |
| 12 Hold Drawbridge for Others |
| 13 Drop Drawbridge from Neutral |
| 14 Hold Portcullis for Others |
| 15 Lift Portcullis |
| 16 Push Down French Ramps |
| 17 Lift French Ramps for Others |
| 18 Hold Sully Door for Others |
| 19 Open Sully Door from Neutral |
| 20 Limbo |
| 21 Climb Tower |
| 22 Defend |
| 23 Dislodge Self |
| 24 Dislodge Others |
| 25 Hold Low Bar Flap Open |

Example: 2016 game - Stronghold

| Tasks | Auto | Teleop | Quals | Elims | Required Skills | Beneficial Skills |
|---------------------|------|--------|-------|-------|------------------------|-------------------|
| Reach Defense | 2 | | | | 1 | |
| Cross Low Bar | 10 | 5 | | | 1,3,20 | |
| Cross French Ramps | 10 | 5 | | | 1,3,16 | 17 |
| Cross Portcullis | 10 | 5 | | | 1,3,15 | 14 |
| Cross Moat | 10 | 5 | | | 1,3,4 | |
| Cross Ramparts | 10 | 5 | | | 1,3,4 | |
| Cross Drawbridge | 10 | 5 | | | 1,3,13 | 12 |
| Cross Sally Door | 10 | 5 | | | 1,3,19 | 18 |
| Cross Rough Terrain | 10 | 5 | | | 1,3,4 | |
| Cross Rock Wall | 10 | 5 | | | 1,3,4 | |
| Boulder Top | 10 | 5 | | | 1,6,9,10 | 2,3,4,5,7,8,11 |
| Boulder Bottom | 5 | 2 | | | 1,2,3,5 | 4,6,7,8,9,11 |
| Climb Tower | | 15 | | | 1,2,3,21 | 4 |
| Challenge Tower | | 5 | | | 1,2,3 | 4 |
| Capture Tower | | | 1RP | 25 | 1,2,3 | 4 |
| Breach Defenses | | | 1RP | 20 | 1,2,3,4,13,15,16,19,20 | 12,13,15,17,18 |

Game Analysis: Match Strategies

- How do you actually play the game?
 - Don't talk about robot designs yet!
 - A fun activity is playing a human game to compare different strategies

Robot archetypes:

- Scorer
 - Accomplish the “main” game task
- Supporter
 - Accomplish “side goals”
- Endgame/Bonus
 - Get the “end game” or “bonus” points
- Defense
 - Prevent opponents from scoring 10 points is as good as you scoring 10 points
- Robots can be none to many of these

Typical Strategies:

- Shootout
 - Ignore the opponents and just score
- Counterplay
 - Use one or more robots to interrupt the other alliance's game plan
- Starvation
 - Deny the opposing alliance any opportunity to score
- Chokehold
 - Accomplish some set of tasks that makes it impossible to lose control
- Think about both your scoring potential and the *differential* to your opponents

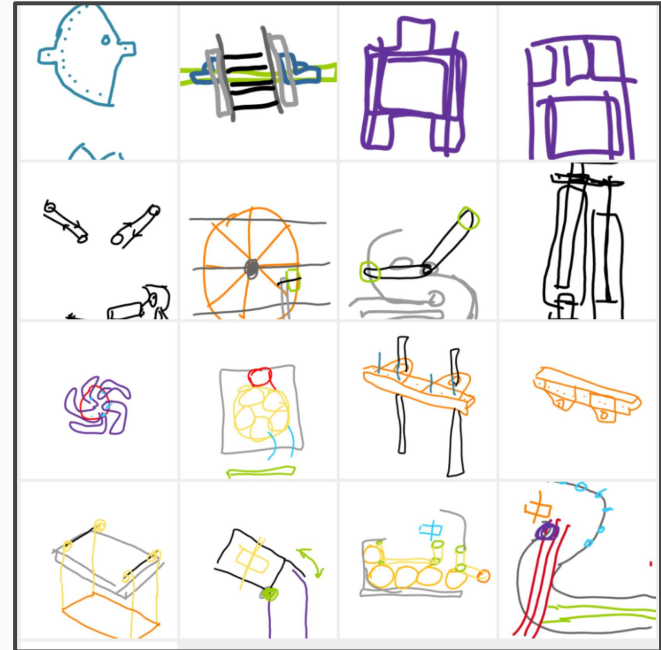
Game Analysis: Match Strategies

- You have to know what you want to do before you can figure out how to do it
- Rules of thumb
 - Elite teams can do 8 full field cycles per match in perfect conditions
 - The best teams will do this a few times a season
 - Middle tier teams can do 4 cycles per match and average maybe 2-3
- Be realistic



Game Analysis: Robot Concepts

- Start to scribble overall robot concepts
 - These should accomplish the match strategies you described
 - These should match the Robot Skills list to accomplish game tasks that you prioritized
 - Think back to “Robot Points” - how much complexity can you plan on?
 - Use anything to communicate- whiteboards, MS Paint, sketch app on your phone, the back of a placemat at a restaurant
 - The details will come eventually. Maybe.



Design Selection: Focusing Your Strat

- Narrow down robot concepts based on goals and feasibility
 - 2-3 concepts to further analyze is a good target
- Think about how these robots will play the game in an alliance
 - Can the design be successful solo?
 - Is the design reliant on Alliance partners?
- List which game tasks are required for selected concepts
 - This will help prioritize robot functions
 - Drive should almost always be a top priority (very few exceptions)

Design Selection: Tradeoffs + Priorities

- Making the right decisions will determine the fate of your season
 - Mutually exclusive tradeoffs?
 - Speed vs power
 - Complexity vs durability
 - Wide vs long frame
 - High vs low center of gravity (easier shot vs tippy robot)
 - Prioritization
 - Which mechanism do we focus on first?
 - Use your strategic priorities to decide the design process
 - Time
 - Driver practice vs. programming vs. mechanism tweaks

Design Selection: Wait and try it?

There's only so much that you can talk about around a table

- Some decisions have to be informed by prototyping and testing
 - Which material works best for this gamepiece?
 - How hard is it to pick this up off the carpet?
- If different design paths depend on radically different mechanisms, can you use testing to focus on a better option?
 - If a game involves scoring balls in a high goal (2020, 2017, 2016, 2014...) and you're considering multiple launchers (flywheel, catapult, puncher...) maybe testing will eliminate one early on

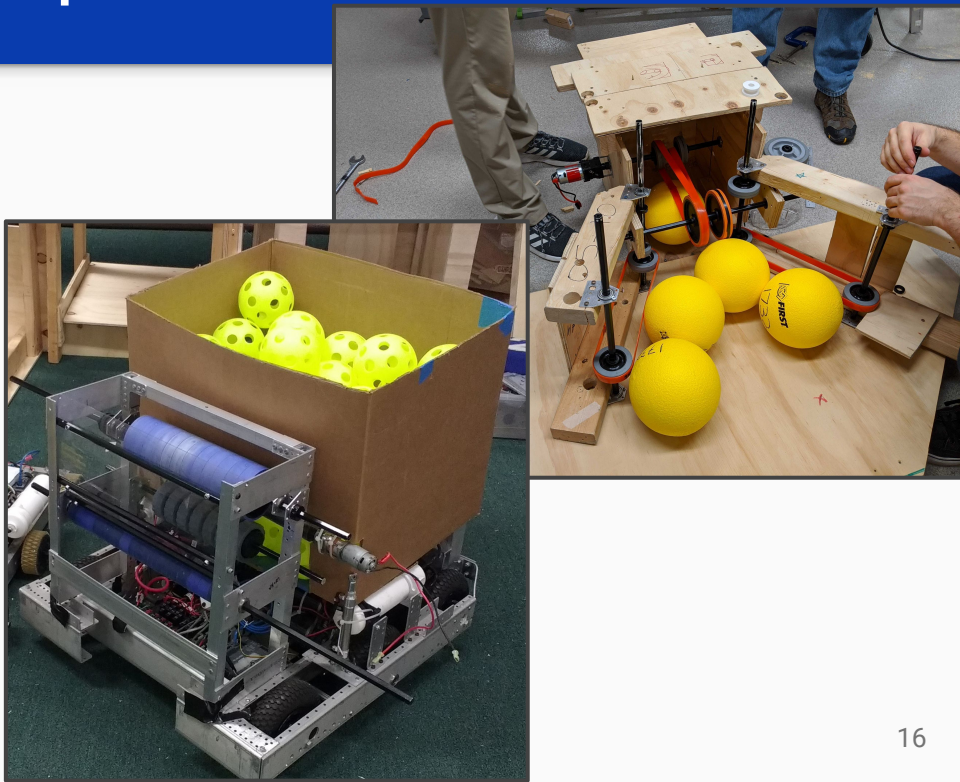
Design Selection: Wait and copy?

Steal from the best.

- Check past games!
 - If a game has a horizontal pull-up bar, what did teams do in 2020, 2018, 2016, 2013...
 - “Ok cool, telescoping or unfolding arms, not a grappling hook.”
- Are there any teams around you or online who want to work together or show ideas?
 - Teams are a different mix of “Open” or “Secret”
 - #Openalliance on Chiefdelphi
 - “Robot in 3 days”
 - Literally, just search YouTube

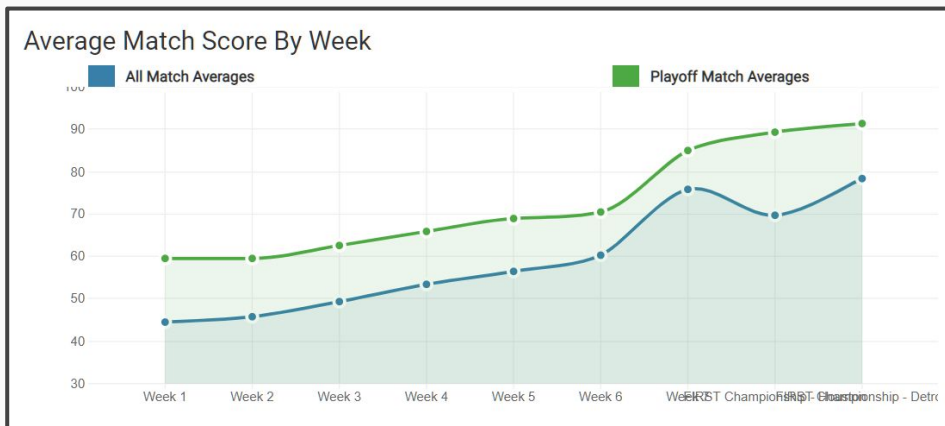
Design Selection: Gamepiece “Flow”

- How are different Robot Skills related?
 - How do different mechanisms rely on each other?
- Gamepiece “Flow”
 - How does a gamepiece get to the goal?
 - Where is the bottleneck?
 - Put differently, it doesn't matter if the scorer is the best in the world if nothing gets to it
 - Examples
 - An intake feeds an indexer which feeds a scorer.
 - A claw is moved on an elevator to get to the scoring height



Design Selection: Feature Ramp

- How much can you work on at a time?
 - What's most important?
 - Drivetrain > Endgame > Main Scoring > Secondary Scoring?
 - Block out space for a mechanism, ignore it, and get back to it later
- What features matter when?
 - The level of play will get better. You only have to beat the teams at your event!
- Examples:
 - 2020 color wheel
 - 2016 low goal
 - More advanced autonomous

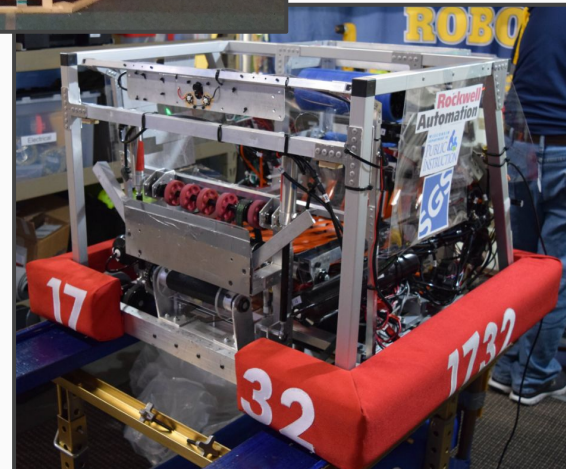
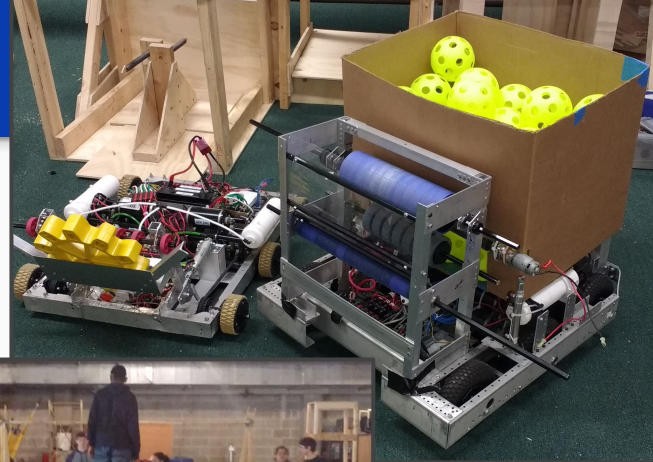


Design Selection: Making a Decision

- It shouldn't be an argument
 - Data from analysis, prototypes and other teams should make it a more objective conversation
- When things escalate:
 - Decision matrix?
 - More testing? Prove it.
 - "A good plan violently executed now is better than a perfect plan executed next week."
 - Also, it won't be perfect next week...
 - IF it comes down to voting, someone will always walk away mad.

Example: 2017 Steamworks, Team 1732

- Goals:
 - Win a Regional and be competitive at Champs
- Resources:
 - Budget for practice bot
 - Drillpress/bandsaw machining (no CNC)
 - Local practice field (Thanks Robotigers 2830!)
- Game analysis + priorities
 1. Gear scoring + Climbing
 2. Driving
 3. Better autonomous routines
 4. Ball scoring
- Feature Ramp-up:
 - Regional 1: Gear scoring, climbing
 - Regional 2: Practice ball scoring, but play to win
 - Champs: Faster climbing, faster ball scoring
 - Offseason: Moved climber up for faster climb



Homework

- Old games
 - Rules/videos
 - <https://www.firstinspires.org/resource-library/frc/archived-game-documentation>
 - Match footage
 - <https://www.thebluealliance.com/>

Questions?

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team1732.com/resources